

Hall Sensors

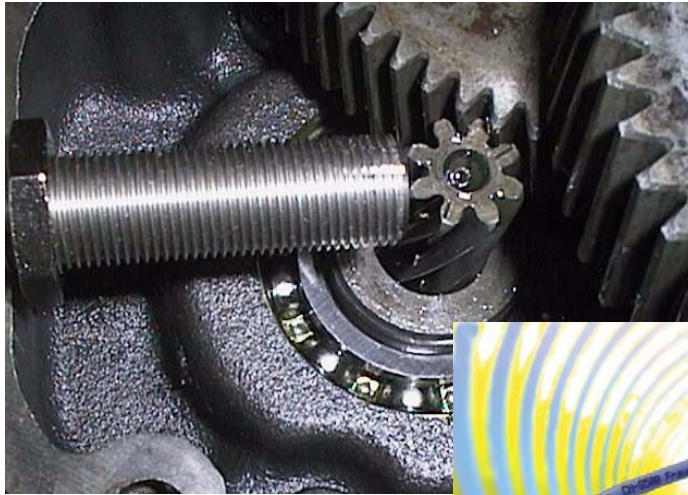
Magneto-resistive Sensors

Gear pick-up devices

Non-contact potentiometers

Magnetic encoders for rotary applications

Magnetic encoders for linear applications



- ▶ Gear pick-up devices
- ▶ Non-contact potentiometers

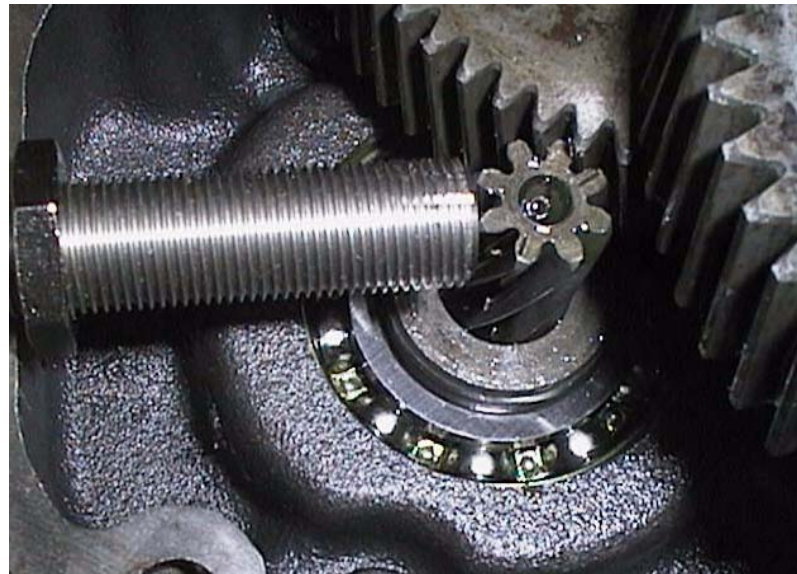


- ▶ Rotary encoders
- ▶ Linear encoders

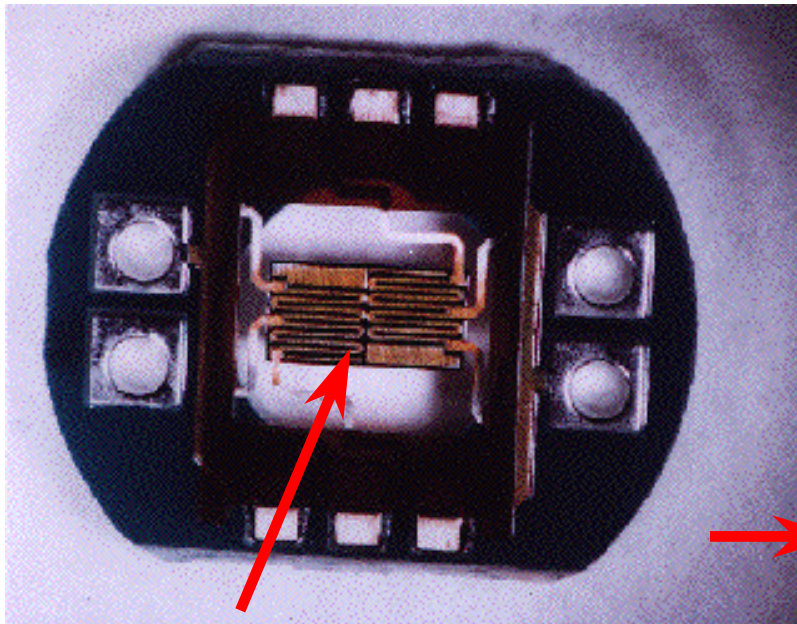


Hall Sensors

Gear pick-up devices

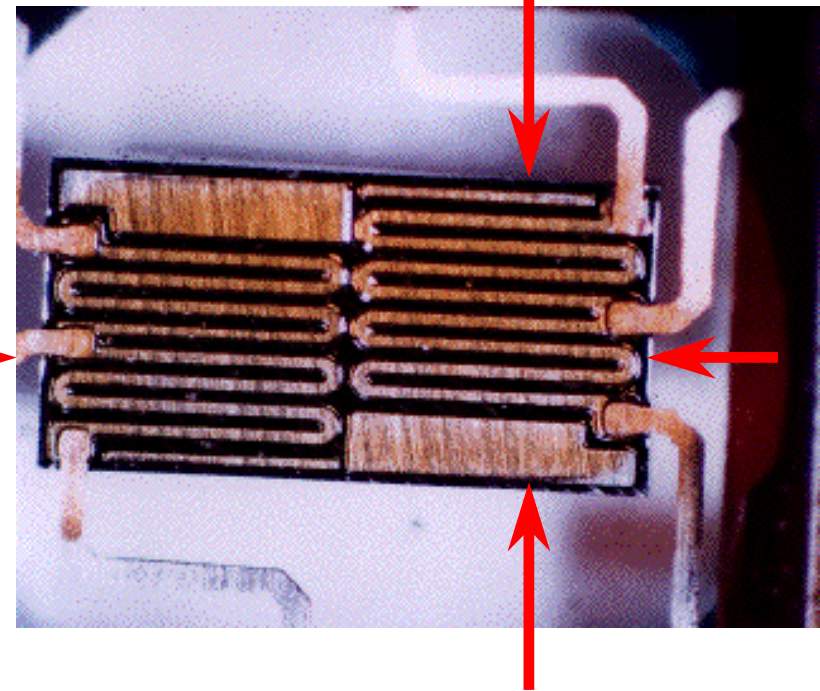


The magnetically biased Hall chip
The “heart” of gear pick-up devices

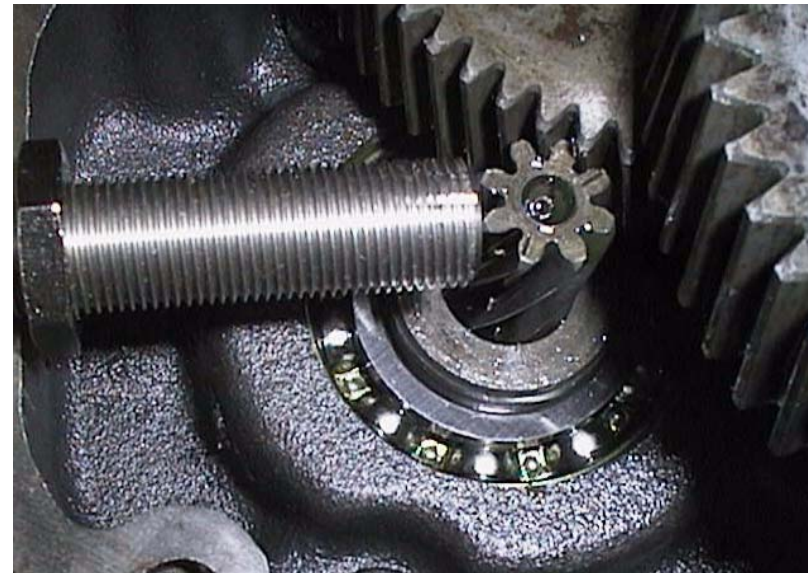


Position of biasing magnet

Chip size 1.6 x 2.7 mm

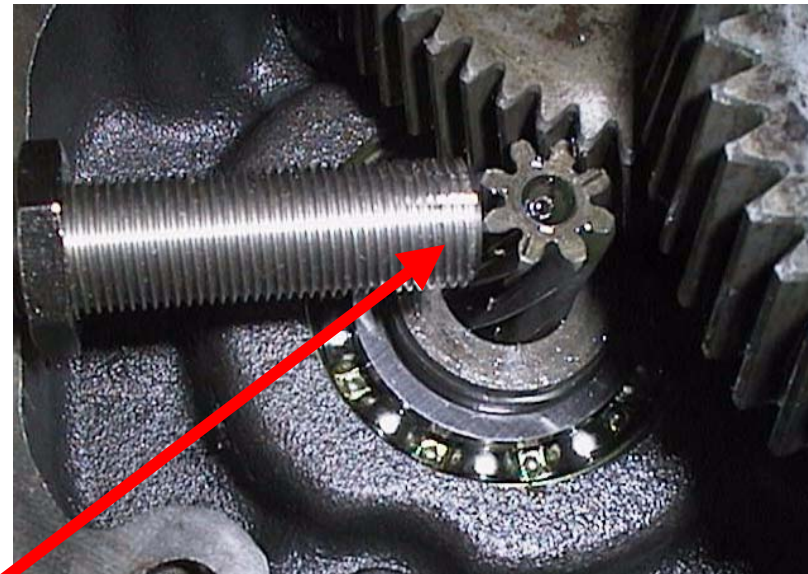


- ▶ MHRM 12G5501/S14
- ▶ Replacement for field plate sensors (IP 67)
- ▶ Single channel device
- ▶ Resolution module ≥ 1
- ▶ Does not have to be aligned with the gear teeth



- ▶ Specification sheets: www.baumerelectric.com

- ▶ IHRM 12P1501
 - Single output
- ▶ MHRM 12G2501
 - Dual outputs
- ▶ Full metal steel housings including sensing face
- ▶ IP 68 / 20 bar rating
- ▶ Resolution module ≥ 1
- ▶ Must be aligned with the gear teeth



- ▶ Higher switching frequencies than inductive sensors
 - Inductive sensors up to 5 kHz only
 - Hall sensors up to 20 kHz
- ▶ Finer resolution than inductive sensors
 - Resolution of inductive sensors > module 2
 - Resolution of Hall sensors > module 1
- ▶ Hall sensors are much easier to adjust than proxies

Applications for gear pick-up devices

- ▶ Primarily used for the reliable detection of ferromagnetic gear wheels and toothed racks
- ▶ Hall sensors replace incremental encoders in certain applications
- ▶ Gear wheel RPM monitoring
- ▶ Tachometer generator
- ▶ Determination of sense of rotation of gear wheels
- ▶ Direction of movement of toothed racks

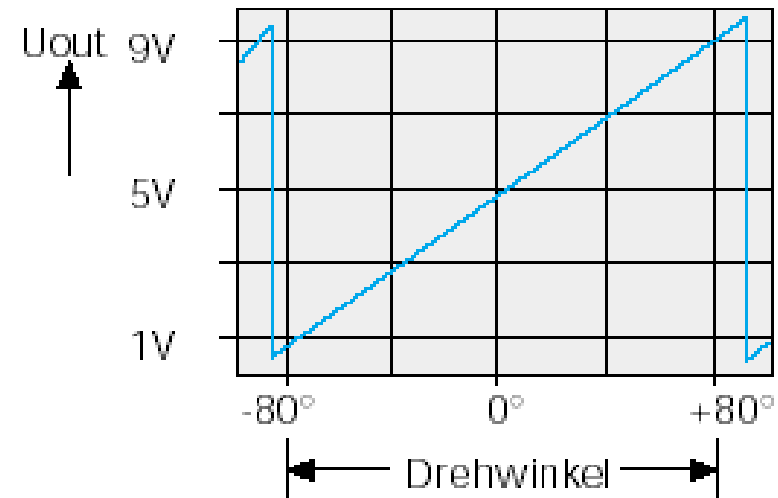
USPs Hall gear pick-up devices

- ▶ Can be easily retrofitted in existing machinery
- ▶ Fast and easy set-up requiring little adjustment
- ▶ Insensitive to vibration
- ▶ Tolerant against dust and humidity
- ▶ Sealed to IP 67 / IP 68 like inductive sensors
- ▶ No moving parts, no bearings
- ▶ No need for expensive mechanical couplings
- ▶ Absolutely no wear
- ▶ Wide working temperature range (-40°C to +120°C)
- ▶ For long operation cycles



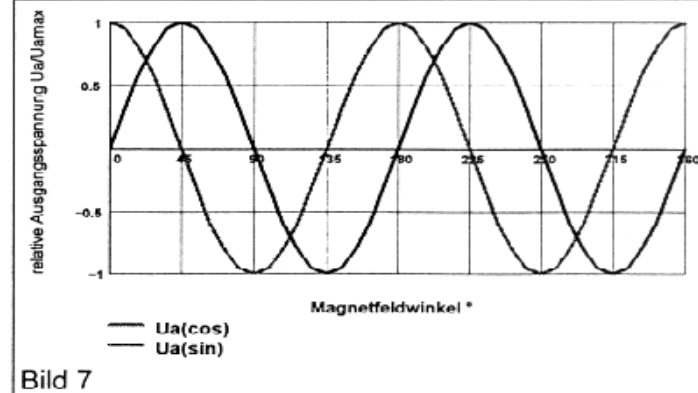
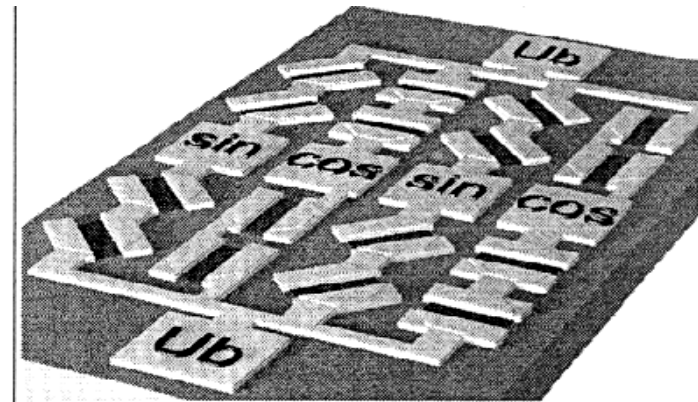
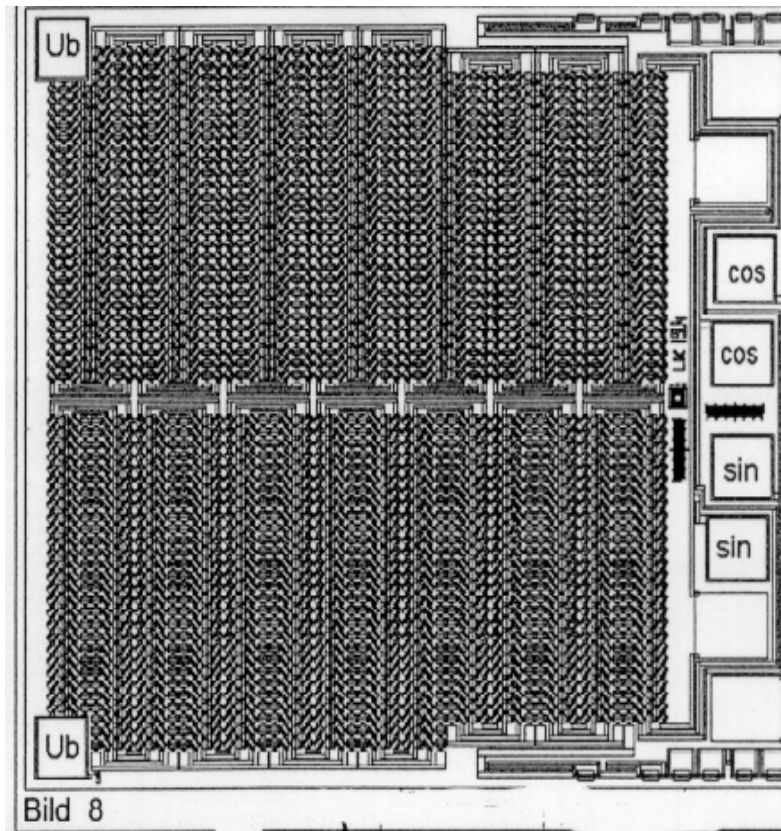
Non-contact potentiometers
based on
Giant Magneto Resistors

- ▶ Sinusoidal outputs
- ▶ Linear current output signal
- ▶ Linear voltage output signal



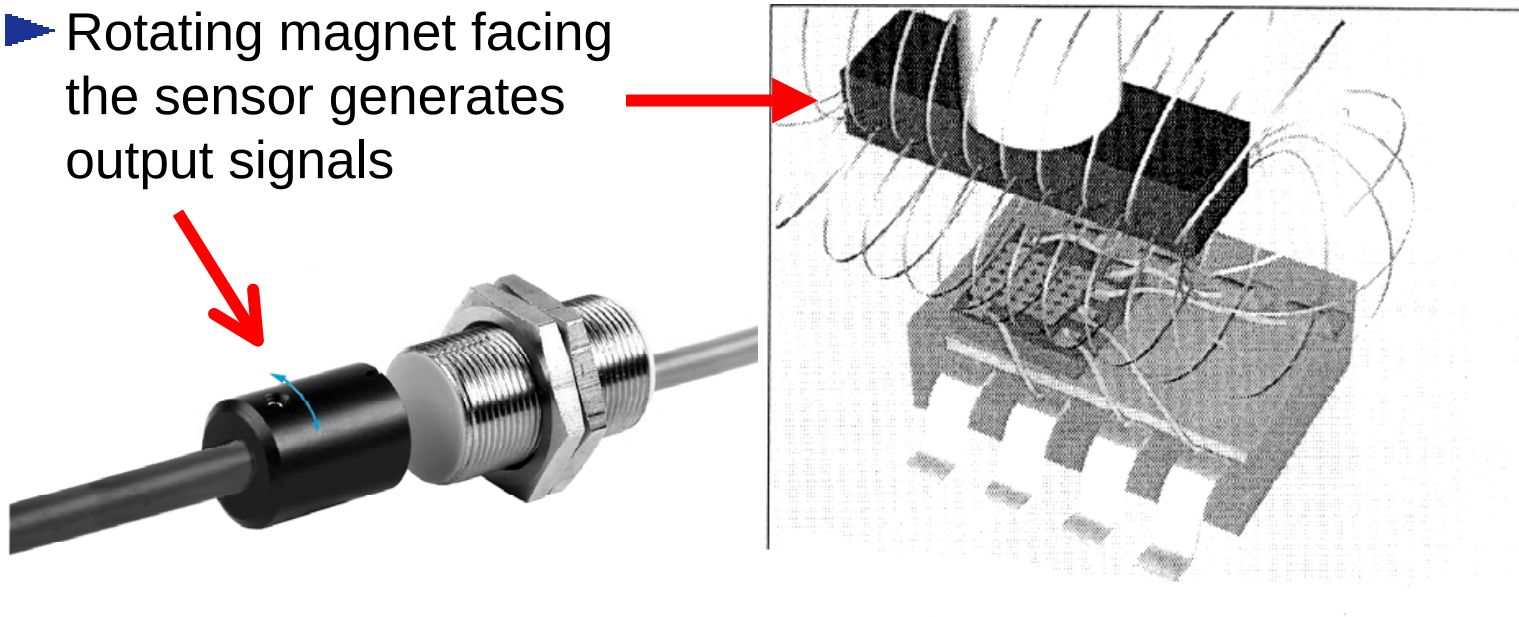
Giant Magneto Resistors

The “heart” of rotary & linear motion control devices



The working principle of non-contact potentiometers

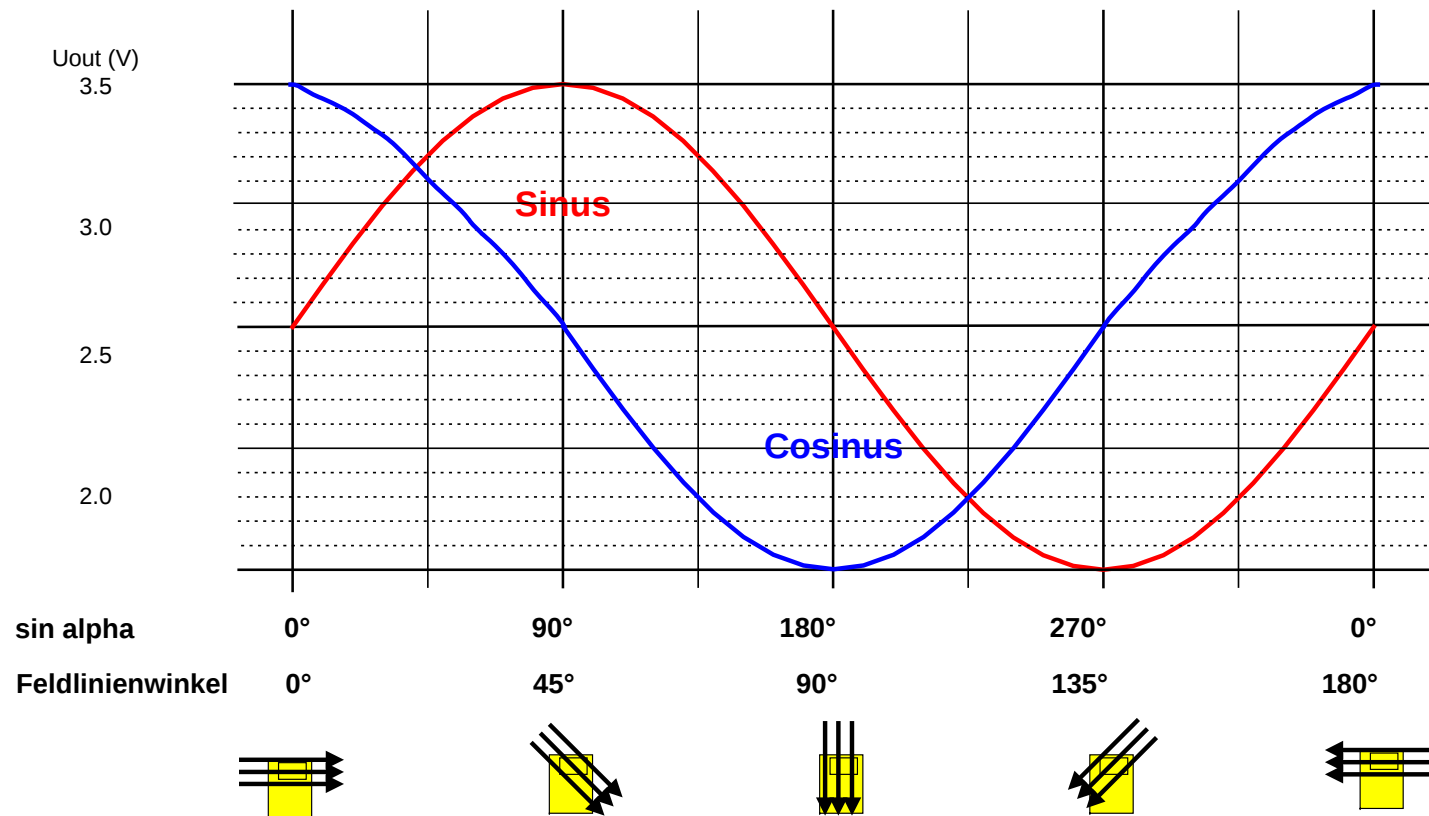
- ▶ Rotating magnet facing the sensor generates output signals



- ▶ Two full sine and cosine signals per turn

Chip output signal / half turn of rotor

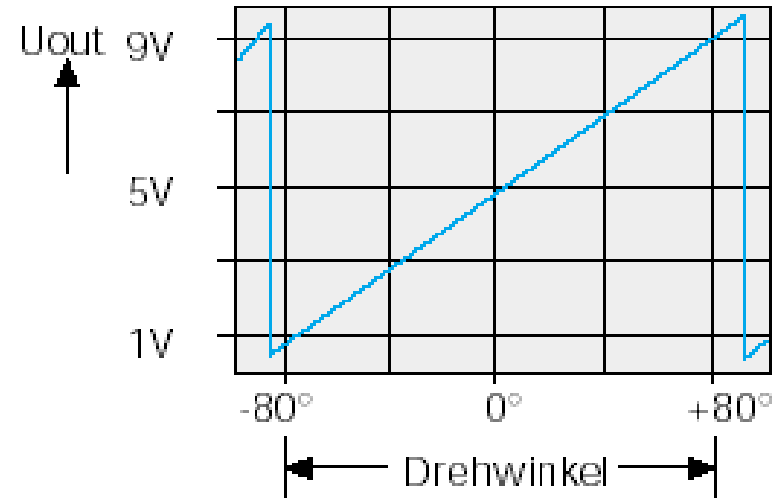
LK15 Winkelsensor (elektrisches Ausg.signal)



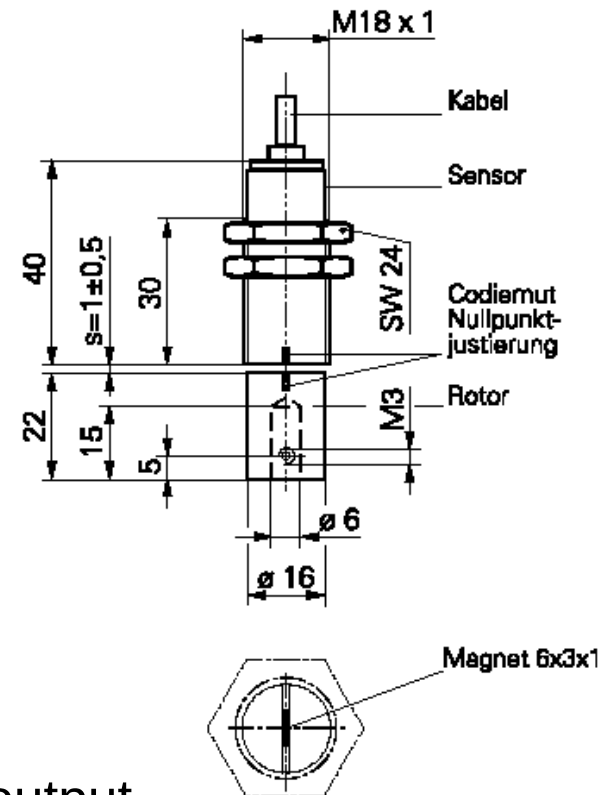
Magnet sensors

Non-contact potentiometers

- ▶ 160° angle of rotation
- ▶ Linear VDC output signals
- ▶ MDRM 18U9501
 - ▶ 0.3...4.7 VDC
- ▶ MDRM 18U9524
 - ▶ 1...9 VDC
- ▶ 20 kHz frequency response
- ▶ absolute voltage output



- ▶ 120° angle of rotation
- ▶ Linear current output signal
- ▶ 24 VDC voltage supply range
- ▶ MDRM 18I9524
 - ▶ 4...20 mA
- ▶ 20 kHz frequency response
- ▶ absolute 4...20 mA current output



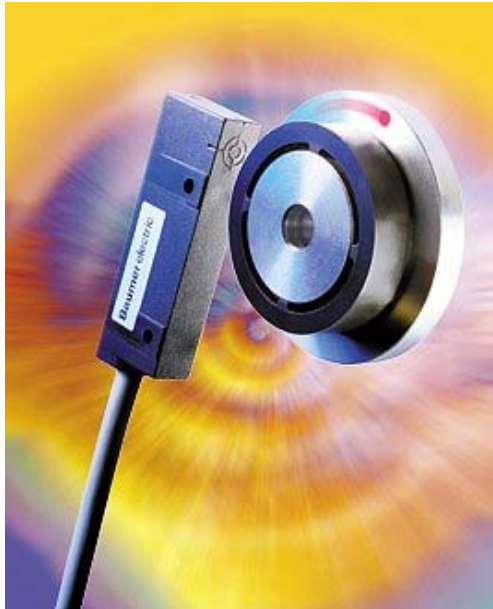
- ▶ Reliable replacement for mechanical potentiometers
- ▶ 20 kHz frequency response
- ▶ With linear (absolute) voltage & current signals
- ▶ Sine output signals
- ▶ For long operation cycles
- ▶ Absolutely no wear
- ▶ No moving parts
- ▶ Sealed to IP 67



- ▶ Require magnet rotor 123344 for proper operation

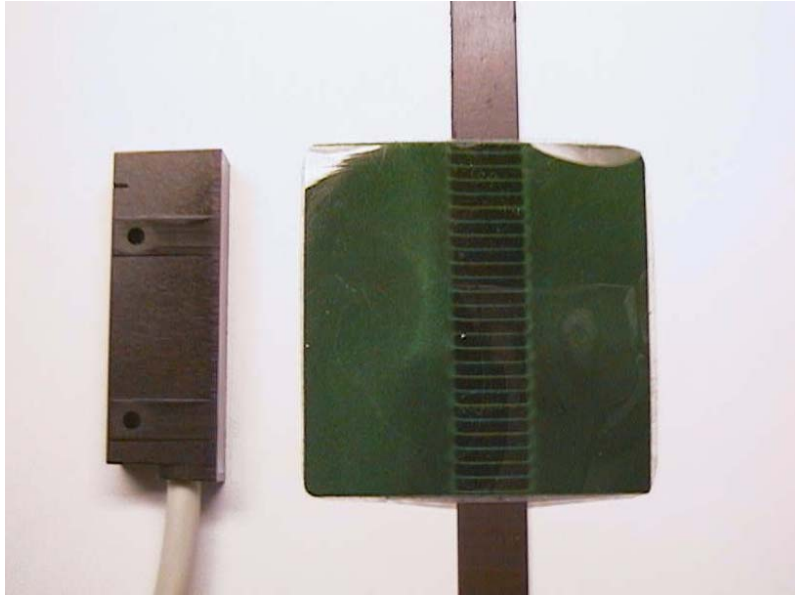
Magneto-resistive Sensors

Magnetic encoders for rotary applications



Magnet sensors

Ring magnets & magnetic strips

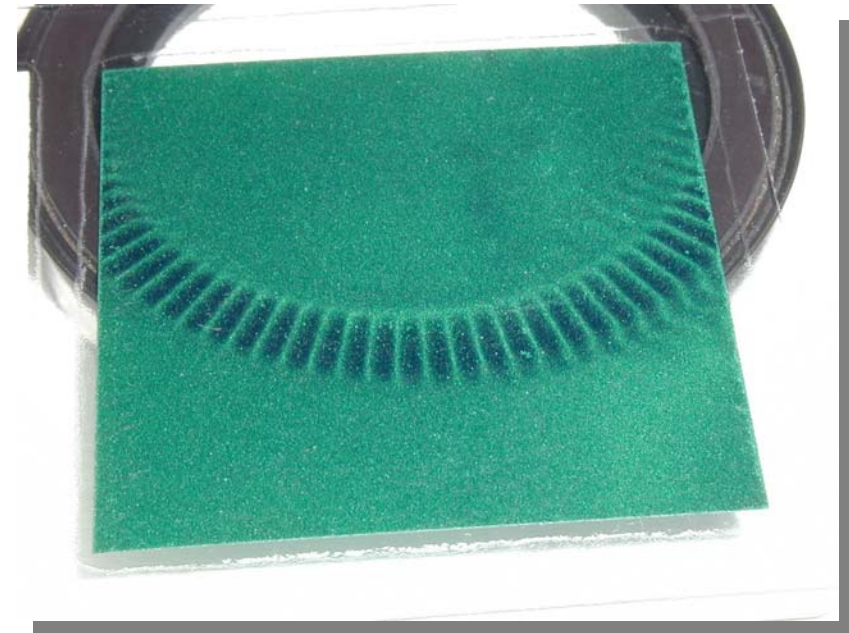


Magnetic strips

- ▶ Ferrite
- ▶ Plasticized ferrite

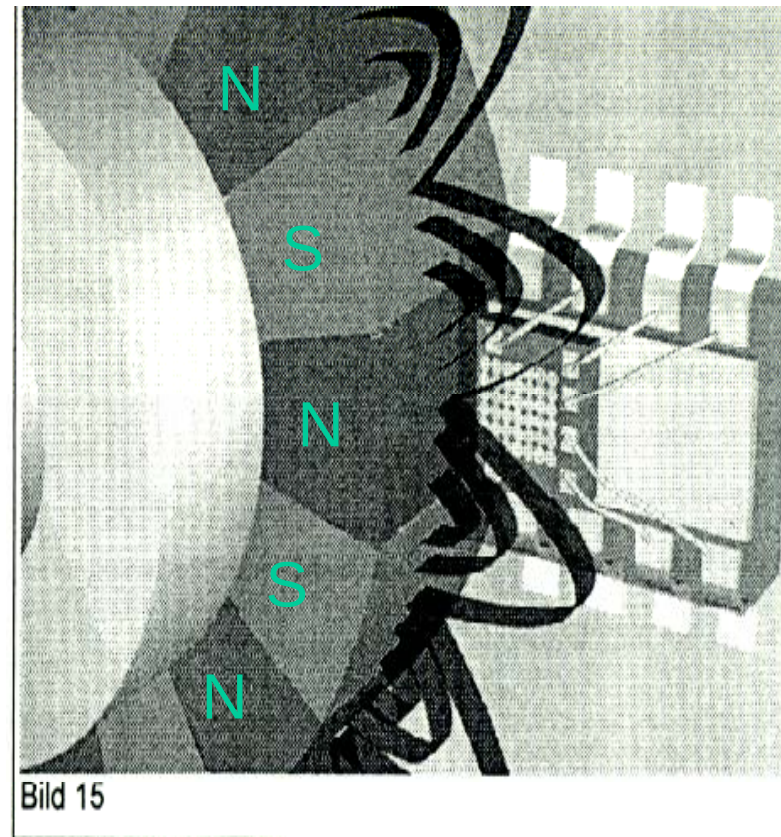
Ring magnets

- ▶ Ferrite
- ▶ Plasticized ferrite
- ▶ Front or side magnetized



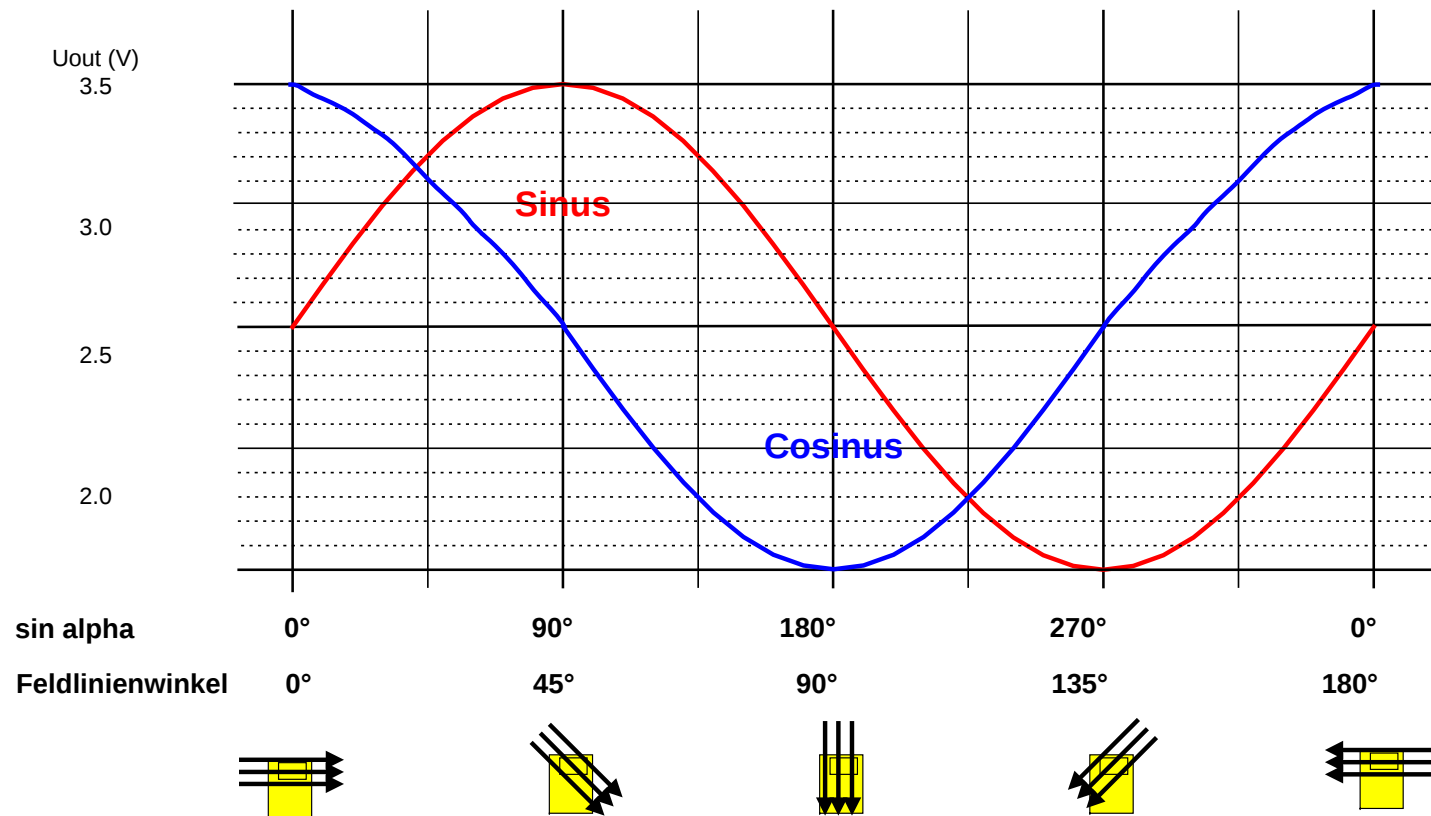
The working principle of rotary magnet encoders

- ▶ Rotating ring magnet facing the sensor generates output signals
- ▶ Provides a full sine and cosine signal per pole



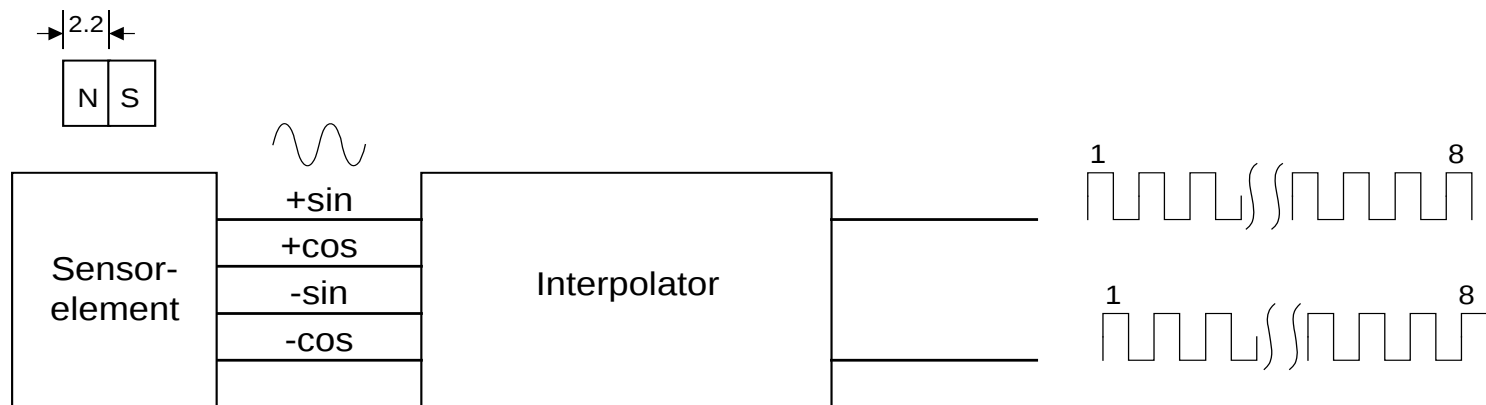
Chip output signal / pole of magnet ring

LK15 Winkelsensor (elektrisches Ausg.signal)



Increasing the number of pulses per pole
by applying signal interpolation

- ▶ 64-fold signal interpolation generates
- ▶ 64 pulses per pole and channel



How to calculate the max number of steps per revolution based on

- ▶ Number of poles of the ring magnet (64)
- ▶ Interpolation factor of the sensor (64)

A standard 64 pole ring magnet generates:

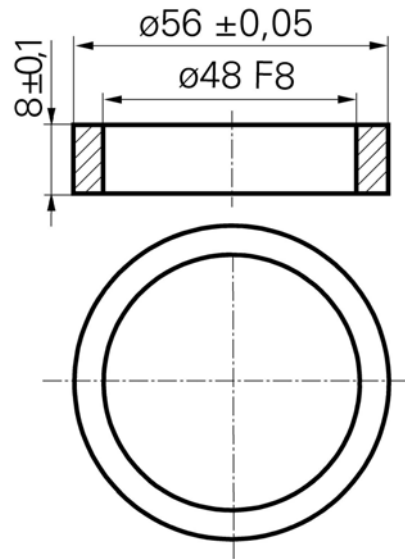
- ▶ 64 pulses per pole on channel A
- ▶ 64 pulses per pole on channel B

= 4096 pulses on both channels per full turn (360° mechanical)

= 16384 ppr when using quadrature type of external signal processing

Available ring magnets and magnet rotors

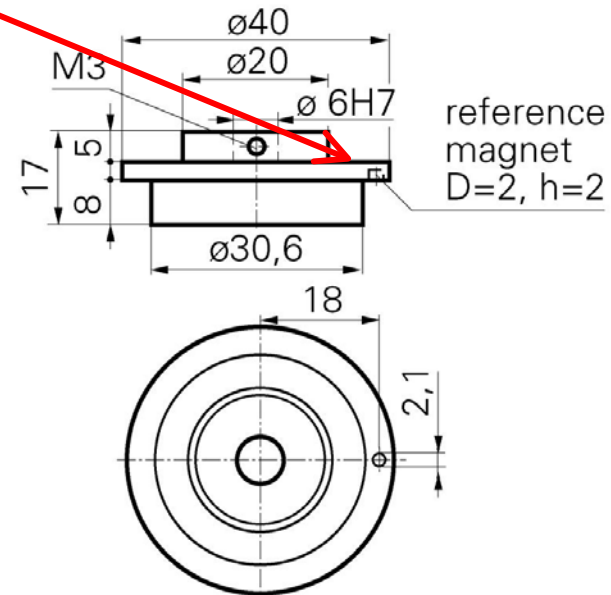
- ▶ 32 poles dia 30 mm
- ▶ 36 poles dia 30 mm
- ▶ 40 poles dia 30 mm
- ▶ 64 poles dia 56 mm



Special magnet rotors for sensors with integrated 0-pulse



- ▶ 32 poles dia 40 mm
- ▶ 36 poles dia 40 mm
- ▶ 64 poles dia 56 mm



Controlling rotary motion with magnet sensors

MDFK 10G8124/N64

- ▶ Two channels 90° phase shifted
 - ▶ With zero pulse
 - ▶ 64 fold interpolation
 - ▶ Push-pull output
 - ▶ Up to 16384 steps per rev.
- ▶ Active face at center of housing

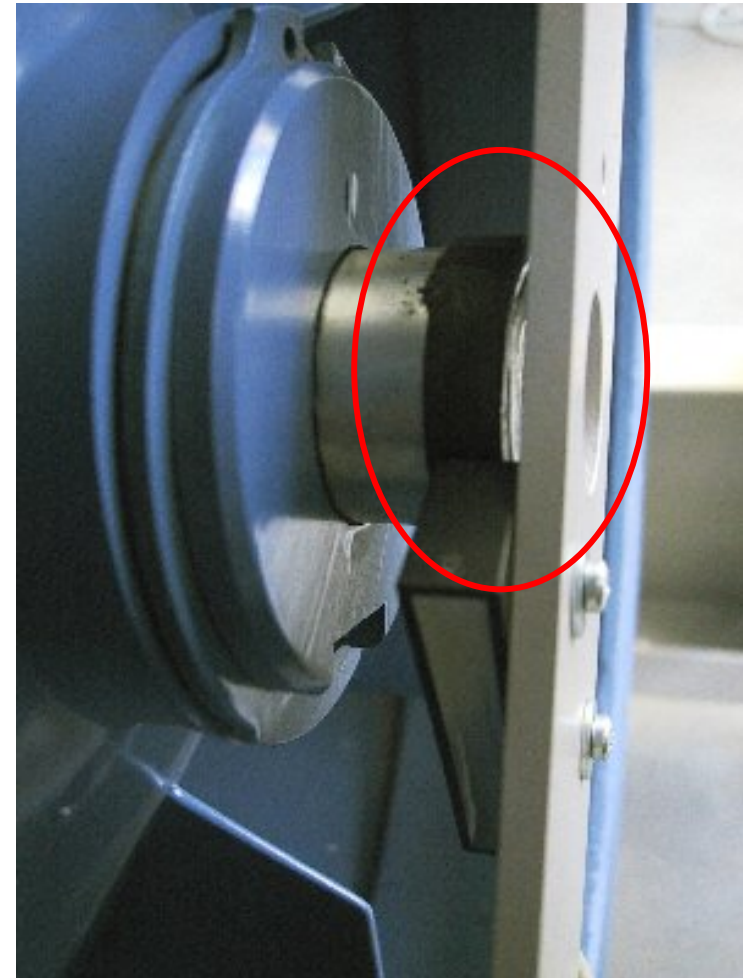


Where to find applications for magnet sensors

- ▶ Dusty and dirty environments
- ▶ Wood, glass, ceramics, stone, plastics, textile, rubber, cement, paper & cardboard processing industries
- ▶ Outdoor applications of all sorts (sealed to IP 67)
- ▶ In applications where space is at a premium

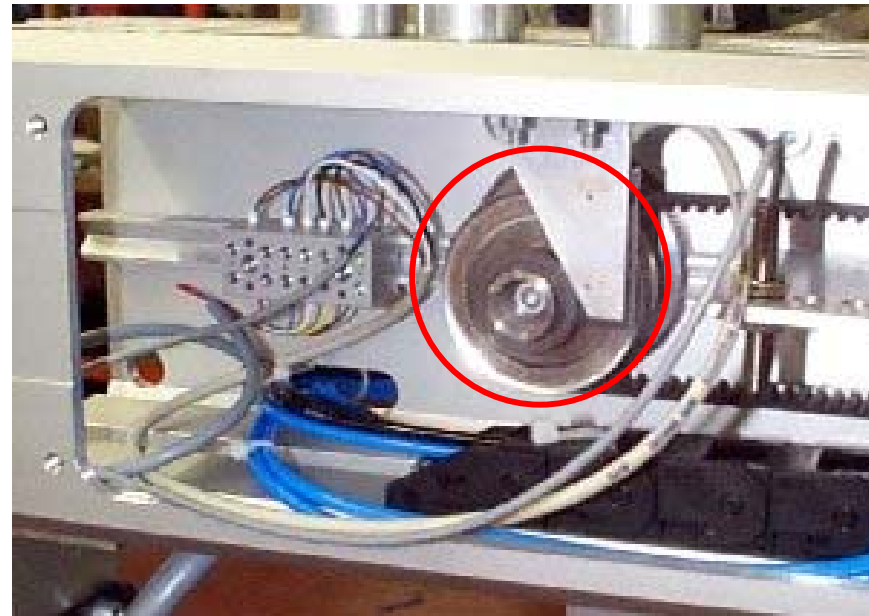
Application: textile machine, main drive control

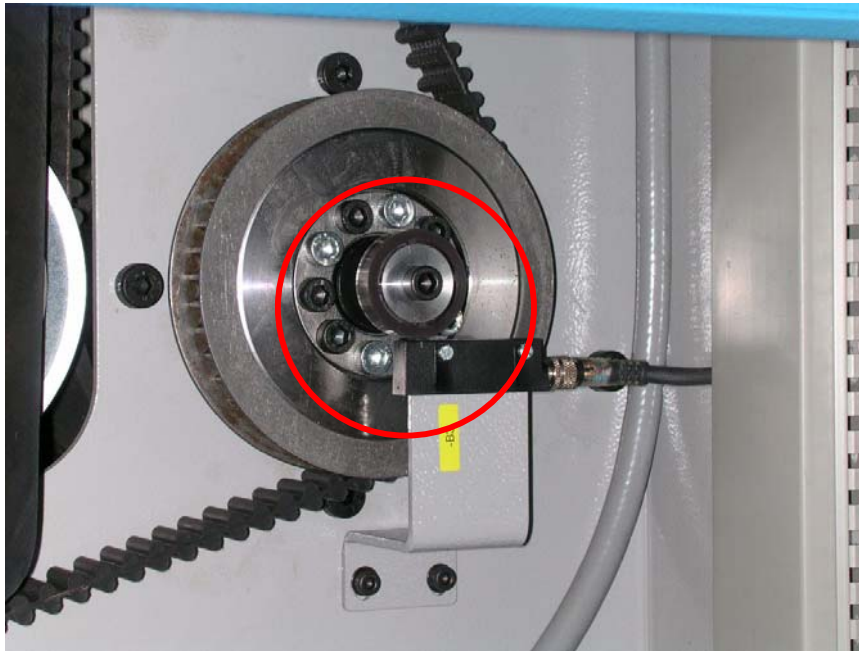
- ▶ MDFK 08G2124
- ▶ Monitoring of shaft rotation
- ▶ Standard 32 pole ring magnet
- ▶ Directly mounted on shaft
- ▶ Standard interpolation factor
- ▶ No marker pulse required
- ▶ Replacing optical encoder



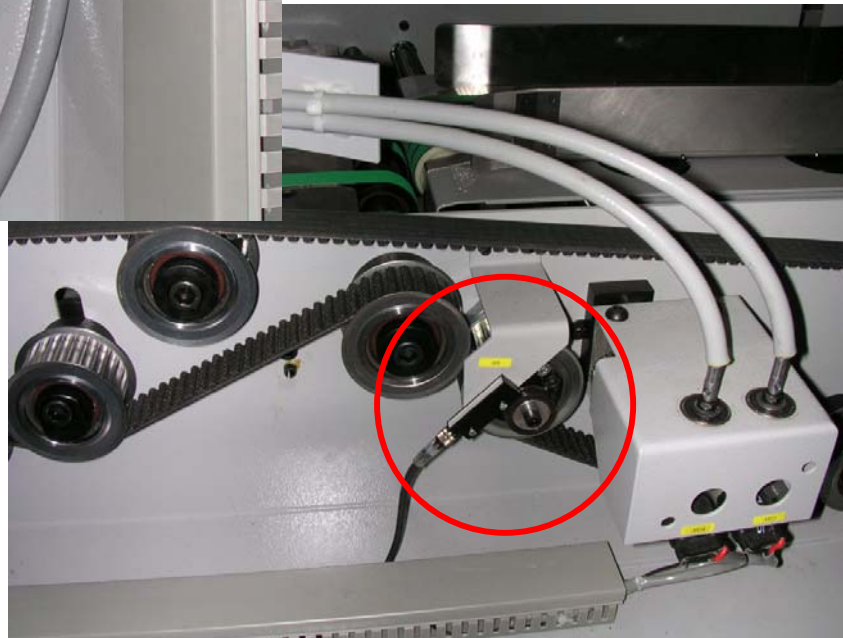
Application: on sieve printing machine

- ▶ MDFK 08G2124
- ▶ Scraper feed control
- ▶ 36-pole ring magnet
- ▶ Glued onto steel shaft
- ▶ Old solution: gear wheel and inductive sensor
- ▶ Advantage of MDFK:
 - ▶ Higher resolution
 - ▶ U/D recognition





- ▶ MDFK 08G2124/N16
- ▶ Connector version
- ▶ 32 pole ring magnet
- ▶ Attached to drive pulleys



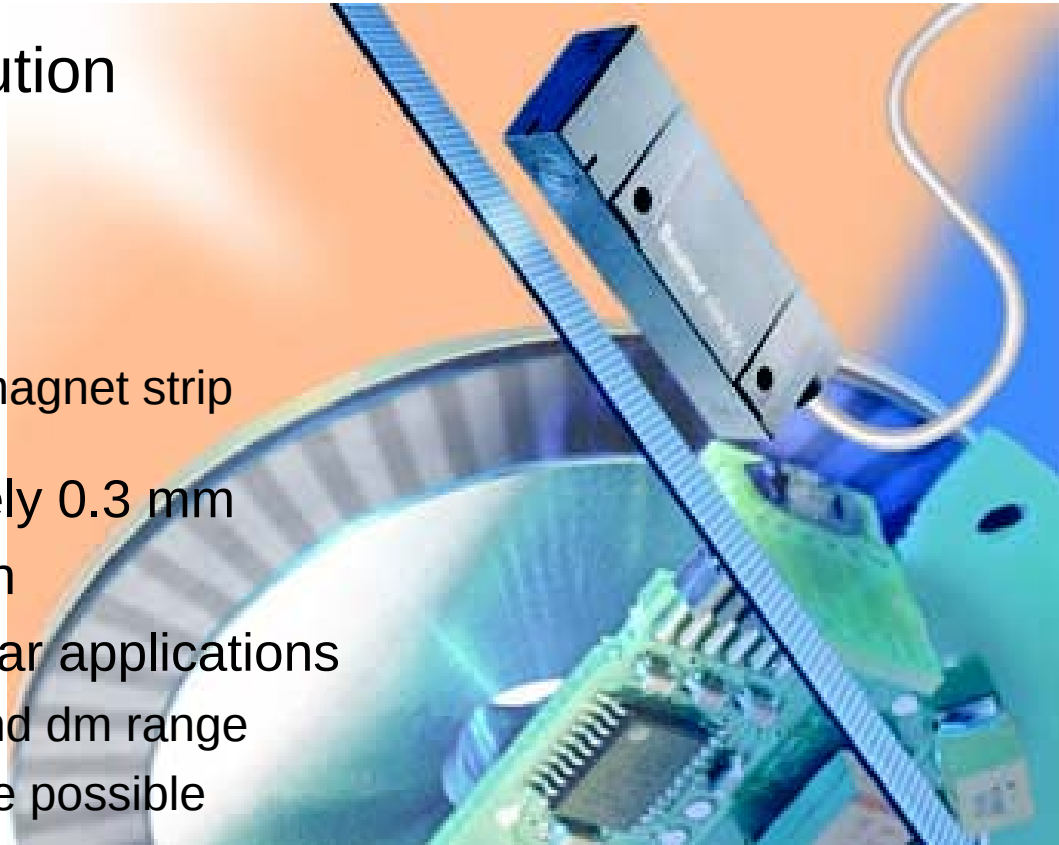
Magneto-resistive Sensors

Magnetic encoders for linear applications

Featuring 10 μ m resolution

MLFK 08T7105/N25X

- ▶ High resolution
 - < 10 μ m @ 1mm magnet strip
- ▶ Air gap approximately 0.3 mm
- ▶ very compact design
- ▶ For incremental linear applications
 - Preferred in cm and dm range
 - Several meters are possible
- ▶ 5VDC with RS 422
- ▶ Output signals A+, A-, B+, B-
- ▶ 25 pulses / 100 steps per pole



Controlling linear motion with magnet sensors

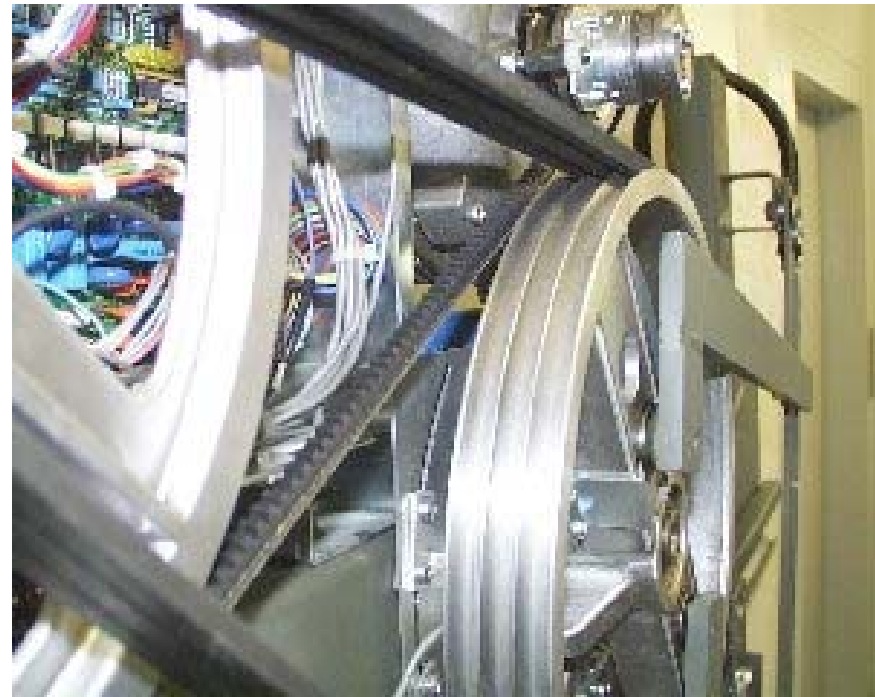
MLFK 10G2124/N100

- ▶ Two channels 90° phase shifted
 - ▶ 100 fold interpolation
 - ▶ Push-pull output
 - ▶ 5 micrometer resolution
-
- ▶ Active face at center of housing



Application: elevator technology, position feedback

- ▶ Application of MLFK 08G2101
- ▶ Magnetized ribbon attached to the side of the big belt wheel
- ▶ MLFK 08 provides feedback for the control electronics
- ▶ Control device for locking mechanism of elevator doors



Customer benefits of magnet sensors

- ▶ Magnetic sensors require little mounting space
- ▶ No flexible couplings required
- ▶ No moving parts (ball bearings, shafts, optical discs etc.)
- ▶ Protection class IP 67 (fully potted & sealed)
- ▶ Tolerant to dust, dirt and vibration
- ▶ Ring magnets & magnetic strips can be glue-fixed
- ▶ Magnetic strip even adjusts to contours of carrier